

Komodo FXCL CameraLinkTM over Fiber acquisition system Hardware Reference and Installation Guide

(Part-No. KY-FXCL)

January 2016



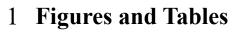






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Revision History

| Version | Date | Notes |
|---------|----------|-----------------|
| 0.1 | 02.02.16 | Initial Release |
| | | |
| | | |

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2.1 Safety Precautions

With your Komodo FXCL system components in hand, please take a minute to read carefully the precautions listed below in order to prevent unnecessary injuries to you or other personnel or cause damage to property.

- Before using the product, read these safety precautions carefully to assure correct use.
- These precautions contain serious safety instructions that must be observed.
- After reading through this manual, be sure to act upon it to prevent misuse of product.



In the event of a failure, disconnect the power supply.

If the product is used as is, a fire or electric shock may occur. Disconnect the power supply immediately and contact our sales personnel for repair.

If an unpleasant smell or smoking occurs, disconnect the power supply.

If the product is used as is, a fire or electric shock may occur. Disconnect the power supply immediately. After verifying that no smoking is observed, contact our sales personnel for repair.

Do not disassemble, repair or modify the product.

Otherwise, a fire or electric shock may occur due to a short circuit or heat generation. For inspection, modification or repair, contact our sales personnel.

Do not touch a cooling fan.

As a cooling fan rotates in high speed, do not put your hand close to it. Otherwise, it may cause injury to persons. Never touch a rotating cooling fan.

Do not place the product on unstable locations.

Otherwise, it may drop or fall, resulting in injury to persons or failure.

If the product is dropped or damaged, do not use it as is.

Otherwise, a fire or electric shock may occur.

Do not touch the product with a metallic object.

Otherwise, a fire or electric shock may occur.

Do not place the product in dusty or humid locations or where water may splash.

Otherwise, a fire or electric shock may occur.

Do not get the product wet or touch it with a wet hand.

Otherwise, the product may break down or it may cause a fire, smoking or electric shock.

Do not touch a connector on the product (gold-plated portion).

Otherwise, the surface of a connector may be contaminated with sweat or skin oil, resulting in contact failure of a connector or it may cause a malfunction, fire or electric shock due to static

electricity.

Do not use or place the product in the following locations.

- Humid and dusty locations
- Airless locations such as closet or bookshelf
- Locations which receive oily smoke or steam
- Locations close to heating equipment
- Closed inside of a car where the temperature becomes high
- Static electricity replete locations
- Locations close to water or chemicals

Otherwise, a fire, electric shock, accident or deformation may occur due to a short circuit or heat generation.

Do not place heavy things on the product.

Otherwise, the product may be damaged.

Be sure to drain static electricity from body before you touch any electronics component

The electronic circuits in your computer and the circuits on Komodo board are sensitive to static electricity and surges. Improper handling can seriously damage the circuits. In addition, do not let your clothing come in contact with the circuit boards or components.

Otherwise, the product may be damaged.

2.2 Disclaimer

This product should be used for converting CameraLink interface to fiber optic interface. KAYA Instruments assumes no responsibility for any damages resulting from the use of this product for purposes other than those stated.

Even if the product is used properly, KAYA Instruments assumes no responsibility for any damages caused by the following:

- Earthquake, thunder, natural disaster or fire resulting from the use beyond our responsibility, acts caused by a third party or other accidents, the customer's willful or accidental misuse or use under other abnormal conditions.
- Secondary impact arising from use of this product or its unusable state (business interruption or others).
- Use of this product against the instructions given in this manual or malfunctions due to connection to other devices.

KAYA Instruments assumes no responsibility or liability for:

- Erasure or corruption of data arising from use of this product.
- Any consequences or other abnormalities arising from use of this product, or damage of this product not due to our responsibility or failure due to modification.

Repair of this product is carried out by replacing it on a chargeable basis, not repairing the faulty devices. However, non-chargeable replacement is offered for initial failure if such notification is received within two weeks after delivery of the product.



3.1 Overview

Komodo FXCL system is the industry most advanced Camera Link image acquisition system without range limitations. The system uses fiber optic cables to provide high resolution image acquisition interface for distances up to 40km in single-mode and up to 300m in multi-mode, while each Camera Link Full interface translated to single fiber cable. The Komodo FXCL system is capable of receiving video streams from Camera Link Full camera while such interface supports standard Camera Link bitrates up to 100MHz. This system is ideally suited for industrial, defense and aerospace Machine Vision Systems and applications. The system consists of Komodo Fiber frame grabber and CameraLink to Fiber device. The remote unit converts CameraLink interface to fiber optic interface. The Komodo Fiber FXP system uses a high performance flow through DMA to transmit video streams to computer memory through PCIe interface with minimal latency. This product also provides GPIO for machine control signals, such as triggers, shaft encoders, exposure control and general I/O, which can be control aside video stream acquisition.

The Frame Grabber utilizes PCIe Gen3 x8 links for communication with Host PC for video uploading and configuration.

3.2 Features

- Solves distance limitation of Camera Link
- Extention for distances up to 40km in single-mode and up to 300m in multi-mode
- Plug and Play, no need to configure
- Camera Link Full (Decca) support
- Link redundancy feature over separate fiber cable
- Up to 8 CL Full cameras with single Komodo Fiber Frame Grabber
- Camera Link Full over single fiber cable
- PCIe Gen3 x8 Half-length card
- Up to 144 Gb image buffer
- Camera controls and triggers
- Per-link LED indication on card bracket

- Flexible machine I/O:
 - 4 TTL configurable I/Os
 - 4 LVCMOS configurable I/Os
 - 2 LVDS inputs
 - 2 LVDS outputs
 - 4 opto-isolated outputs
 - 4 opto-isolated inputs
 - 8 quadrature rotary encoders
 - Integrated strobe controller
 - 2 RS232 interfaces (On remote unit)
 - One RS422/RS385 interface (On remote unit)
- Camera Link 2.0 compliant
- Power over Camera Link support
- Multiple Camera synchronization
- Multiple Frame Grabbers synchronization
- MDR connectors for camera interface
- GUI interface
- Supporting Windows and Linux OS
- API for developing custom applications
- Plug-ins modules for Matlab, HALCON and Labview
- GenTL support
- Data rates up to 10 Gbps per link
- Transfer Rate of up to 60 Gbps
- 0°C to 70°C operating environment temperature

3.3 Product Applications

- AOI
- Printing inspection
- Broadcasting and sports analytics
- High-speed DVRs
- Defense remote systems
- Surveillance

3.4 Related documents and accessories

Documents:

• Komodo Fiber Reference Guide

Accessories:

- CL cables
- Fiber cables (Multi or Single mode)
- GPIO Extension Panel



4.1 System Structure

The Komodo FXCL system consists of a CameraLink camera, an extender box (KY-CL2F) that translates the CameraLink interface to fiber optic interface and a Komodo Fiber frame grabber that is able to acquire video directly from fiber optic cables.

The Komodo Frame Grabber supports multiple modes of configuration and system topology. Few of these are presented in following diagrams.

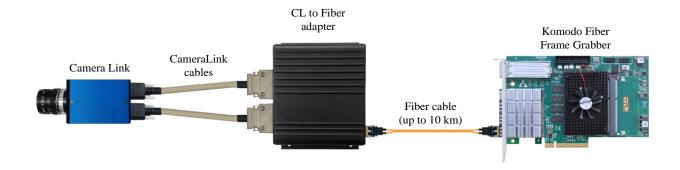


Figure 1: KY-FXCL topology block diagram

4.2 External View of the Komodo Fiber frame grabber

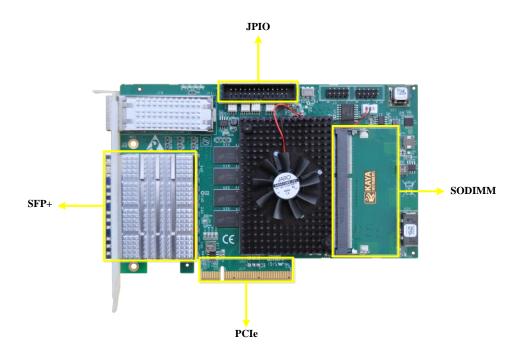


Figure 2: Komodo board external view

4.3 External View of the KY-CL2F

Each *KY-CL2F* unit is housed in a compact, metal enclosure. Each unit has a power connector, 2 Camera Link connectors (MDR), SFP+ cage, 2 x RJ45 connectors for GPIO and a Mini USB Terminal interface, as shown in Figure 3.

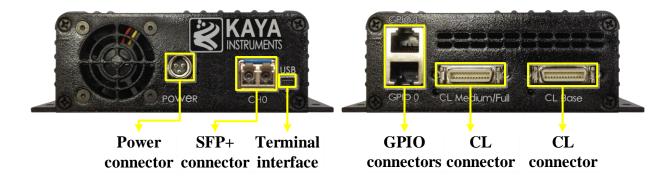


Figure 3: KY-CL2F external view

Each of the CL and SFP+ connectors is paired with a status LED and there is a system status LED (see 7.2 section describing the LED status).

Each unit also has mount ears for an easy and secure installation on any flat surface.



5 Mechanical Specifications

5.1 Essentials to get started

To begin using your Komodo FXCL system, you must have the following:

- ✓ A computer with the following:
 - Processor with an Intel 64-bit architecture, or equivalent.
 - An availably x4 (or x8 or x16) PCIe slot. Gen 3 support is recommended to faster data transfer.
 - Predator Application installation
- ✓ Camera Link camera
- ✓ Camera Link cables
- ✓ Fiber optic cables

NOTE: KAYA Instruments doesn't guarantee compatibility with all computers that have the above specifications. Please, consult KAYA representative for any specific issue.

6 Installation and Configurations

6.1 Installation instructions

The typical Komodo FXCL system is connected as described in Figure 4:

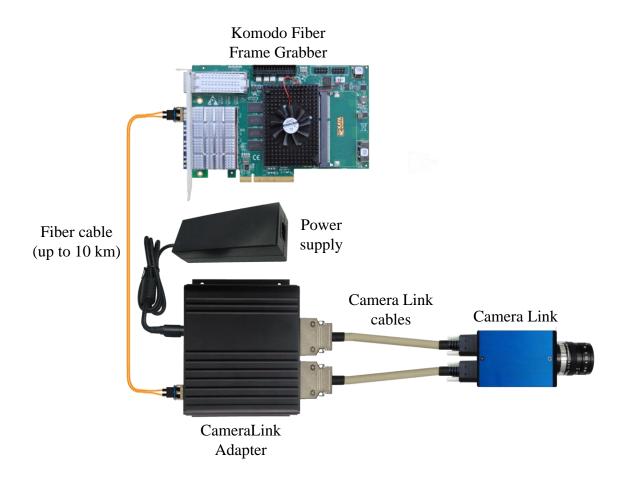


Figure 4: Komodo FXCL system connection diagram

The first stage of the system installation is Komodo Fiber board installation as described in section 6.1.1 below. The second stage is connection of KY-CL2F box and camera as described in section 6.1.2.

6.1.1 Komodo Fiber board installation

Before system installation the Komodo Fiber board should be installed into host computer.

Komodo Fiber board is standard PCIe card with 8 lanes connector.

It can be installed in any PCIe connector of the motherboard with 8 lanes and up.

Note: Board should be installed before you install your software.

- 1. Before installing, turn off the power of the computer and its peripherals.
- 2. Firmly insert the Komodo Fiber board to PCIe connector of the motherboard.
- 3. Anchor the PCIe bracket to the computer chassis using M3 screw.
- 4. Verify the Komodo board inserted correctly to the PCIe slot.
- 5. Power up the computer.
- 6. After OS is up, you will be asked to install a driver for new Multimedia Device. At this stage, you should cancel the installation.

Under Windows and Linux the compatible drivers for Komodo board will be installed during installation of Komodo App software.

You can install and use multiple Komodo Fiber boards in a single computer.

The number of Komodo boards that can be installed in a computer depends on the number of available PCIe slots.

6.1.2 Completing the Komodo FXCL system installation

In order to properly complete the Komodo FXCL system installation, the following steps must be taken for initial power up:

- 1. Make sure there is no dirt or any other foreign matter inside the SFP+ module, or blocking any of the connectors.
- 2. Make sure that the male connectors on the SFP+ module will align with the female connectors inside the cage.
- 3. Insert the SFP+ module(s) into the *KY-CL2F and Komodo Fiber board* and close the locking mechanism (*).
- 4. Connect the fiber cables between *KY-CL2F and Komodo Fiber board*.

- 5. Connect the CameraLink cables between the camera and **KY-CL2F** unit.
- 6. Connect the Power Adaptor to the KY-CL2F unit. The KY-CL2F requires 24V power supply for proper function and for PoCL power for camera. Please, refer to Electrical specification section of this document for exact Power Supply requirements.
- 7. The power supply connector of the *KY-CL2F* unit shown in Figure 3.
- 8. Turn the camera and the frame grabber on and start your application software.
- (*) The Komodo FXCL system supports the following SFP+ modules:
- 1. KY_SFP_SM_C Allows of up to 10Km connection over single mode fiber cable
- 2. KY_SFP_MM_C- Allows of up to 400m connection over multi-mode fiber cable

Note: to remove the SFP+ module, first remove the fiber cable connected to it, then open the SFP+ module's locking mechanism (see Figure 5 and Figure 6) and remove module.



Figure 5 : Module with locking mechanism closed

Figure 6 : Module with locking mechanism open

6.2 Reducing the fiber optic cable count

The system requires two fiber optical cables in order to properly operate, but sometimes it required transferring the data over smaller number of cables.

Several options listed in the sections below exist in order to reduce the number of required optical cables. Please note that these options are available for single mode fiber infrastructure only.

Please contact KAYA representative for details of those options.

6.2.1 Bidirectional (BIDI) SFP option

This option allows reducing one fiber optic cable from the system. The total required number of cables will be only one.

In this option the SFP in link 0 is replaced by bidirectional (BIDI) SFP that transmits and receives on the same fiber cable. Example connection for four link camera is described in Figure 7.

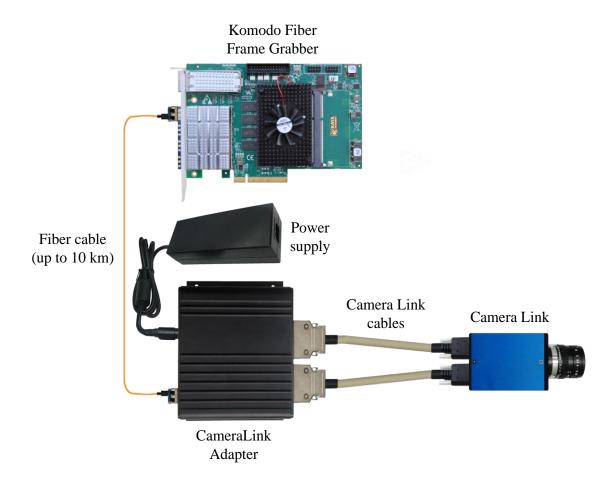


Figure 7: Bidirectional camera link connection



7.1 Komodo Fiber Hardware Reference

This chapter provides information on Komodo board hardware. It covers architecture, features and pin assignments for various connectors.

7.1.1 Komodo Fiber Board Block Diagram

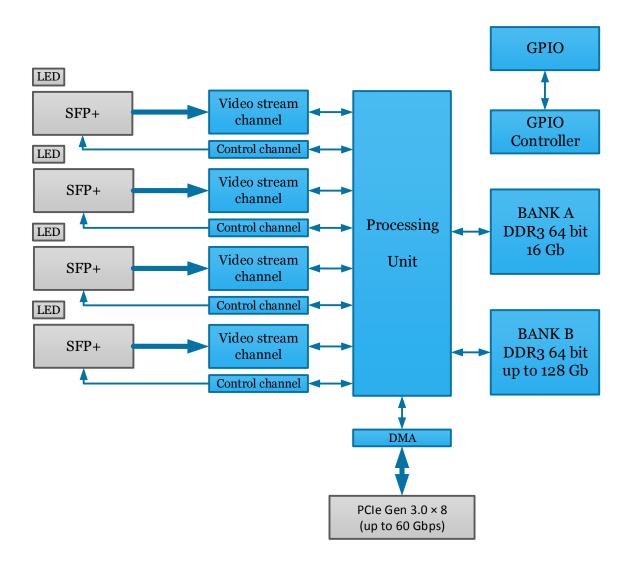


Figure 8: Komodo Fiber Board Block Diagram

7.1.2 Komodo Fiber LEDs

Komodo Fiber is equipped with indication bi-color LED for each SFP connector.

The LEDs' different states are described in

| LED state | Description | |
|-------------------------------------|---|--|
| Solid orange | System is not initialized | |
| Slow pulse red | No camera is connected | |
| Fast flash alternate green / orange | Connection detection in progress | |
| | | |
| Solid green | Camera is connected, no data being | |
| | transferred | |
| Slow pulse orange | Camera connected. Waiting for trigger event | |
| Fast flash green | Camera connected, data is being transferred | |

Table 1.

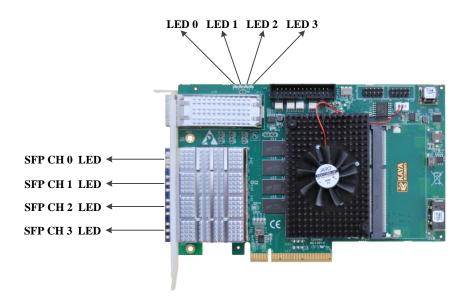


Figure 9: Komodo Board LED's locations

| LED state | Description |
|-------------------------------------|--|
| Solid orange | System is not initialized |
| Slow pulse red | No camera is connected |
| Fast flash alternate green / orange | Connection detection in progress |
| Solid green | Camera is connected, no data being transferred |
| Slow pulse orange | Camera connected. Waiting for trigger event |
| Fast flash green | Camera connected, data is being transferred |

Table 1: Komodo Fiber links status LED's

| In additional to SFP links LEDs, the Komodo Board is equipped with status LEDs. | |
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| LED# | Description | |
|-------|---|--|
| LED 0 | Alive led. Blinks when the board receives clock from PCIe | |
| LED 1 | PCIe L0 state. When lit, indicates that the PCIe interface is powered up at active state. | |
| LED 2 | Gen3 PCIe indicator. When lit indicates that PCIe is working as Gen3. When not lit the boards works either as PCIe Gen1 or Gen2 | |
| LED 3 | Lane's indicator. When lit, indicates that all 8 PCIe lanes are up. If not lit, one or four lanes are up. | |

Table 2: Komodo Fiber board status LED's

7.1.3 Auxiliary Input/Output signals

The auxiliary signal of Komodo Fiber board can be used to initiate on-board events, transmitted to other devices or rerouted from other signals, such as triggers and GPIO's.

Additionally, these auxiliary signals can be used to communicate with complex devices, such as encoders, strobe controls and drive controls.

The GPIOs can be controlled from the API and be set as a trigger sources. The API enables routing of any input to any output as well as to the remote Trigger lines. Please see the API documentation for more information regarding the GPIO configuration.

The GPIOs of Komodo Fiber are routed to single IO header with 2.54 mm (100 th) pitch.

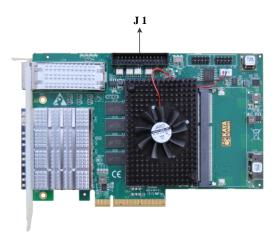


Figure 10: GPIO connectors location

The pinout of IO connector is as described in Table 3.

| Pin Number | Signal Name | Function | Electrical Standard | Description |
|---------------|-------------------------|----------------------|---------------------|---|
| 1 | LVDS Input 0p | LVDS input | LVDS | Positive signal of LVDS pair |
| 2 | LVDS Input 0n | LVDS input | LVDS | Negative signal of LVDS pair |
| 3 | LVDS Input 1p | LVDS input | LVDS | Negative signal of LVDS pair |
| 4 | LVDS Input 1n | LVDS input | LVDS | Negative signal of LVDS pair |
| 5 | LVDS Output 0p | LVDS output | LVDS | Positive signal of LVDS pair |
| 6 | LVDS Output 0n | LVDS output | LVDS | Positive signal of LVDS pair |
| 7 | LVDS Output 1p | LVDS output | LVDS | Negative signal of LVDS pair |
| 8 | LVDS Output 1n | LVDS output | LVDS | Negative signal of LVDS pair |
| 9 | OptoCoupled Output 0 | Opto-Isolated output | Up to 70V | Optically isolated outputs |
| 10 | OptoCoupled Output 1 | Opto-Isolated output | Up to 70V | Optically isolated outputs |
| 11 | OptoCoupled Output 2 | Opto-Isolated output | Up to 70V | Optically isolated outputs |
| 12 | OptoCoupled Output 3 | Opto-Isolated output | Up to 70V | Optically isolated outputs |
| 13 | OptoCoupled Input 0 | Opto-Isolated input | Up to 70V | Optically isolated inputs |
| 14 | OptoCoupled Input 1 | Opto-Isolated input | Up to 70V | Optically isolated inputs |
| 15 | OptoCoupled Input 2 | Opto-Isolated input | Up to 70V | Optically isolated inputs |
| 16 | OptoCoupled Input 3 | Opto-Isolated input | Up to 70V | Optically isolated inputs |
| 17 | OptoCoupled GND | External GND | | Ground signal for opto- isolated signals on this connector. |
| 18 | GND | Board GND | | Reference ground signal |
| 19 | TTL 0 | GPIO | TTL (Open-drain) | General Purpose IO |
| 20 | TTL 1 | GPIO | TTL (Open-drain) | General Purpose IO |
| 21 | TTL 2 | GPIO | TTL (Open-drain) | General Purpose IO |
| 22 | TTL 3 | GPIO | TTL (Open-drain) | General Purpose IO |
| 23 | LVTTL 0 | GPIO | LVTTL | General Purpose IO |
| 24 | LVTTL 1 | GPIO | LVTTL | General Purpose IO |
| 25 | LVTTL 2 | GPIO | LVTTL | General Purpose IO |
| 26 | LVTTL 3 | GPIO | LVTTL | General Purpose IO |

Table 3: J1 connector pinout

The electrical connection of the GPIO connector is described following principal schematic diagram:

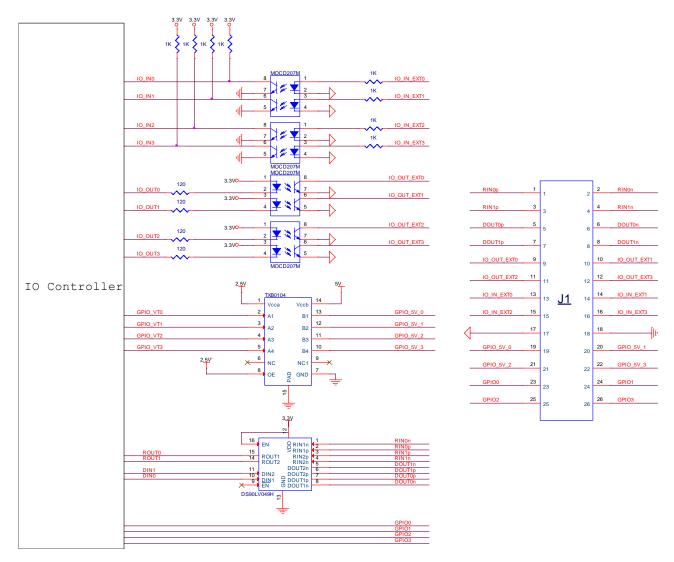


Figure 11: GPIO Connector schematic

7.2 KY-CL2F unit Hardware Reference

This chapter provides information on KY-CL2F unit hardware.

7.2.1 KY-CL2F unit LEDs description

Each unit has several status LEDs, as seen in Figure 12 and .

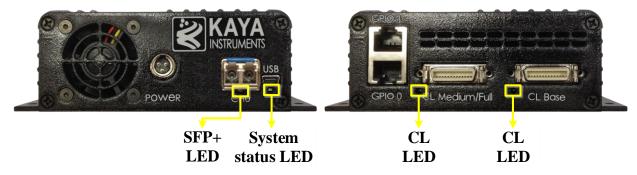


Figure 12.

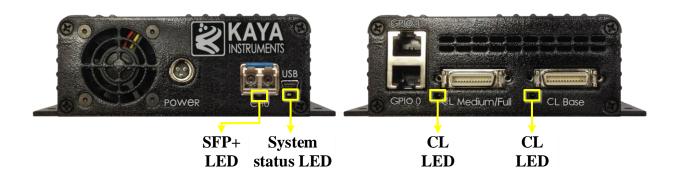


Figure 12: KY-CL2F Fiber side LEDs

Figure 13: KY-CL2F CL side LEDs

The System status LED, located on the Camera link side, always slow pulses in green while the system is ON. While in firmware update mode, this LED slow pulses orange. In any case of system failure, the LED will constantly light orange.

The KY-CL2F LED's behavior is described in Table 4:

| LED state | Condition | |
|----------------|--|--|
| Slow pulse red | No valid CL link detected | |
| Solid red | PoCL failure (Overcurrent/Under voltage/Overvoltage) | |
| Solid green | Camera link is active | |

| Table 4: KY-CL2F status LEDs behavior | | | |
|---------------------------------------|--|--|--|
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The SFP+ LED behavior is described in Table 5:

| LED state | Condition | |
|------------------|-----------------------------------|--|
| Fast flash red | SFP+ is unplugged | |
| Solid red | SFP is not compatible | |
| Slow pulse red | No signal detected on optic fiber | |
| Fast flash green | Link is being established | |
| Solid green | Link is active | |

Table 5 : SFP+ status LEDs behavior

7.3 Power supply

This device requires 12V power supply for proper function. External power supply or user provided 12V must be connected to unit.

Please, refer to Electrical specification section of this document for exact Power Supply requirements.



8.1 KY-CL2F Terminal control

A Mini USB port is available for individual link & general information status and firmware update. The port uses a Silabs CP2101 chip. A driver from the Silabs website might have to be installed on certain PCs to gain access to the terminal port. Free supporting driver can be found at: http://www.silabs.com/products/mcu/pages/usbtouartbridgevcpdrivers.aspx

After driver installation and USB connection is acquired a serial emulated terminal (i.e Tera Term use is recommended) can be used with the following configurations, described in Table 6:

| Parameter | Value |
|--------------|--------|
| Baud rate | 115200 |
| Start bits | 1 |
| Stop bits | 1 |
| Parity | None |
| Flow Control | None |

Table 6 : Serial emulated terminal configurations

The following commands are supported by the terminal; each command must be followed by carriage return (Enter) in order to execute:

| Command | Description |
|----------|--|
| firmware | Sets the system to firmware update mode. See 8.2 chapter for firmware update information |
| status | Prints the system and link status and general information |

Table 7: Terminal commands

NOTE: The commands are not case sensitive.

8.2 KY-CL2F Firmware update

- 1. The extender supports firmware update via USB using a serial emulated terminal. To initiate firmware update the following steps should be taken:
- 2. Connect the USB cable to the extender and acquire connection using Silabs drivers (drivers need to be downloaded manually if an automatic download isn't initiated).

- 3. Open serial emulated terminal (usage of Tera Term terminal is recommended) and set serial communication protocol as described in chapter 8.1.
- 4. In the terminal window type "status" followed by carriage return and checks the current firmware version.
- 5. Choose the firmware update option by entering "firmware" followed by carriage return and wait for the following message: "Now starting firmware update, please start file transfer using XMODEM:"
- 6. At this point all the LEDs will turn off and the "System status LED" will slow pulse orange indicating the extender is ready to receive the firmware binary file. Use the terminal "transfer" capability using the XMODEM protocol to initiate the firmware update.
- 7. If no firmware will be sent during 1 minute, or in case of an error the firmware update will fail and return to previous operation mode.
- 8. A successful update will result in appropriate message and a reboot of the extender to new firmware.
- 9. Check the firmware version by typing "status" followed by carriage return. Make sure that the firmware version matches the version on the firmware update package supplied; that would insure the success of the firmware update operation.

8.3 IO Connector

The extender incorporates two RJ45 connectors to provide GPIO functionality such as TTL, Opto Coupled, RS232 and RS422. The pin-out of the connectors can be found in the tables below.

| Pin number | Name | Description | | |
|------------|--------------------|--------------------------|--|--|
| 1 | TTL0 | Bidirectional TTL signal | | |
| 2 | OptoCoupled Output | Opto Isolated output | | |
| 3 | RS232 RX 0 | RS232 Receive | | |
| 4 | OptoCoupled GND | Opto Isolated Ground | | |
| 5 | GND | Signal ground | | |
| 6 | RS232 TX 0 | RS232 Transmit | | |
| 7 | TTL1 | Bidirectional TTL signal | | |
| 8 | OptoCoupled Input | Opto Isolated input | | |

Table 8: Top I/O connector pinout

| Pin number | Name | Description | | |
|------------|------------|-------------------------|--|--|
| 1 | RS422 RXp | RS422 positive receive | | |
| 2 | RS422 RXn | RS422 negative receive | | |
| 3 | GND | Signal ground | | |
| 4 | RS422 TXp | RS422 positive transmit | | |
| 5 | RS422 TXn | RS422 negative transmit | | |
| 6 | GND | Signal ground | | |
| 7 | RS232 TX 1 | RS232 transmit | | |
| 8 | RS232 RX 1 | RS232 receive | | |

Table 9: Bottom I/O connector pinout



The extender supports configurations of several components using standard Gen<i>Cam interface described in extracted xml file. The xml file, which is embedded in the extender unit, is complaint with Gen<i>Cam standard 2.0. This provides an interactive interface for controlling extender features and setting and controlling the video stream parameters for the Frame Grabber.

9.1 Stream provided features and controls:

- 1. Width width of the image provided by the device (in pixels).
- 2. Height height of the image provided by the device (in pixels).
- 3. CL Mode the CameraLink mode of the connected camera.
- 4. Pixel Format format of the pixels provided by the device.
- 5. Pixel Format is subordinate to the chosen CL Mode. Not all provided Pixel Formats are available for all CL modes. The complete list can be found in Table 10.
- 6. Taps Number of taps of the camera sensor. Not all provided Taps are available for all CL modes. The complete list can be found in Table 10.
- 7. Scan Type Scan type of the sensor of the device. AreaScan(for area cameras) or LineScan(for line scan cameras) can be chosen to define the mode of the scan type.

| CL Mode | Supported Pixel Format | Supported Taps configuration |
|------------|------------------------|------------------------------|
| Lite | Mono8 | 1 tap |
| | Mono10 | |
| Base | Mono8 | 1 tap |
| | Mono10 | 2 taps |
| | Mono12 | 3 taps |
| | Mono14 | - |
| | Mono16 | |
| | RGB8 | |
| Medium | Mono8 | 1 tap |
| | Mono10 | 3 taps |
| | Mono12 | 4 taps |
| | RGB10 | - |
| | RGB12 | |
| Full | Mono8 | 8 taps |
| | RGB8 | - |
| Deca8taps | Mono10 | 8 taps |
| | RGB8 | - |
| Deca10taps | Mono8 | 10 taps |
| _ | RGB8 | - |

Table 10: Supported Pixel Formats and Taps for different CL modes

9.2 Extender Device provided features and controls:

- 1. Device Firmware Version Current Extender firmware version.
- 2. Connection Reset This will issue reset signal for the device video stream in order to reset stream feed connection with the camera.
- 3. Acquisition Start Enables the transmission of the video stream from the extender.
- 4. Acquisition Stop Disables the transmission of the video stream from the extender.
- 5. Uart Baud Rate configure the serial baud rate for serial communication with the connected camera.
- 6. PoCL Control Enables or disables the PoCL on the extender for both channels
- 7. Test Patter Show test pattern
- 8. Save user configurations saves stream and extender configuration to extender's non-volatile memory.

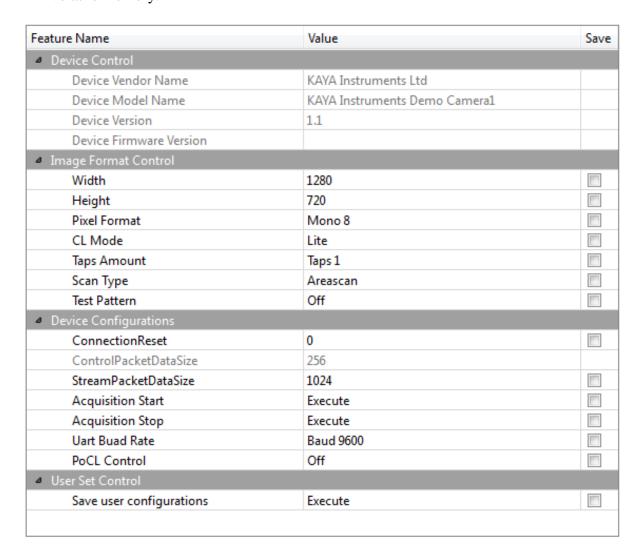


Figure 14: User Configurations

Setting the extender parameters to work with CameraLink camera

- 1. Make sure the Extender has been detected and xml file was fully extracted.
- 2. Set the Width, Height and Scan Type parameters according to current camera stream.
- 3. Set the CL Mode of the camera before setting the Pixel Format and Taps. This is because not all Pixel Format and Taps are supported for all CL Modes.
- 4. In order to save current configurations issue the "Save user configurations" command and this will save current configurations to the extender's non-volatile memory.

10.1 Absolute maximum ratings

| Specification | Values |
|-------------------------------|----------------|
| 3.3V power supply | -1.0V to +7.0V |
| 12V power supply | -0.3V to 14V |
| Storage temperature | -55°C to 125°C |
| Operating ambient temperature | 0°C to 50°C |

Table 11: Komodo Fiber absolute maximum ratings

| Specification | Values |
|------------------------------|--|
| Power supply voltage | 10V to 14V |
| Storage Temperature | -40°C to 105°C |
| Operating Temperature | 0°C to 70°C (Commercial) -40°C to 85°C (Industrial) |
| Opto Isolated input voltage | -6V to 60V |
| Opto Isolated output voltage | -7V to 70V |
| Opto isolated output current | 150mA max |
| TTL I/O input voltage | -0.2V to 6V |
| RS422 input voltage | -6V to 12V |
| RS232 input voltage | -20V to 20V |

Table 12: KY-CL2F Absolute maximum ratings

10.2 Operating conditions

| Parameter Description | | Minimum | Typical | Maximum |
|---|--|---------|---------|---------|
| 3.3 V _{cc} 3.3V Supply voltage from PCIe | | 3.04V | 3.3V | 3.56V |
| 12V V _{cc} 12V Supply voltage from PCIe | | 11.04V | 12V | 12.96V |
| 3.3 I _{cc} (Host) | Supply Current from 3.3V PCIe power rail | - | 2.1A | - |
| 12 I _{cc} | Supply Current from 12V PCIe power rail | - | 2A | - |

Table 13: Komodo Fiber operating conditions

Electrical characteristics for Komodo Fiber board IO's:

| Symbol | Parameter | Condition | Pin | MIN | Тур | MAX | Units |
|--------------------------|-----------------------------------|--|-----------------------------|------|------|-------|-------|
| $ V_{OD} $ | Differential Output | | | 250 | 350 | 450 | mV |
| | Voltage | | | | | | |
| ΔV_{OD} | Change in Magnitude of | | | | 1 | 35 | mV |
| | V _{OD} for Complementary | | | | | | |
| | Output States | $R_L = 100 \Omega$ | | | | | |
| V_{OS} | Offset Voltage | | | 1.12 | 1.23 | 1.375 | V |
| | | | | 5 | | | |
| ΔV_{OS} | Change in Magnitude of | | $\mathrm{D}_{\mathrm{OUT}}$ | | 1 | 25 | mV |
| | Vos for Complementary | | D_{OUT+} | | | | |
| | Output States | | | | | | |
| Ios | Output Short Circuit | ENABLED, | | | -5.8 | -9.0 | mA |
| | Current ⁽⁴⁾ | $D_{IN} = V_{DD}$, $D_{OUT+} = 0 \text{ V or }$ | | | | | |
| | | $D_{IN} = GND, D_{OUT} = 0 V$ | | | | | |
| I_{OSD} | Differential Output Short | ENABLED, $V_{OD} = 0 \text{ V}$ | | | -5.8 | -9.0 | mA |
| | Circuit Current ⁽⁴⁾ | | | | | | |
| I _{OFF} | Power-off Leakage | $V_{OUT} = 0 \text{ V or } 3.6 \text{ V}$ | | -20 | ±1 | +20 | μΑ |
| | _ | $V_{DD} = 0 \text{ V or Open}$ | | | | | |
| Ioz | Output TRI-STATE | $EN = 0 V \text{ and } EN = V_{DD}$ | | -10 | ±1 | +10 | μΑ |
| | Current | $V_{OUT} = 0 \text{ V or } V_{DD}$ | | | | | |

Table 14: Komodo Fiber LVDS Output DC specifications (Driver Outputs)

| Symbol | Parameter | Condition | Pin | MIN | Тур | MAX | Units |
|-----------|-------------------------|--|---------------------|------|-----|-----|-------|
| V_{TH} | Differential Input High | | | | -15 | 35 | mV |
| | Threshold | $V_{CM} = 1.2 \text{ V}, 0.05 \text{ V}, 2.35 \text{ V}$ | | | | | |
| V_{TL} | Differential Input Low | | | -100 | -15 | | mV |
| | Threshold | | $R_{IN^{+}} \\$ | | | | |
| V_{CMR} | Common-Mode Voltage | $V_{ID} = 100 \text{ mV}, V_{DD} = 3.3 \text{ V}$ | R_{IN} - | 0.05 | | 3 | V |
| | Range | | | | | | |
| I_{IN} | | $V_{DD} = 3.6 \text{ V}$ | | -12 | ±4 | +12 | μΑ |
| | Input Current | $V_{IN} = 0 \text{ V or } 2.8 \text{ V}$ | | | | | |
| | | $V_{DD} = 0 \text{ V}$ | | -10 | ±1 | +10 | μA |
| | | $V_{IN} = 0 \text{ V or } 2.8 \text{ V or } 3.6 \text{ V}$ | | | | | • |

Table 15: Komodo Fiber LVDS Input DC specifications (Receiver Inputs)

| Symbol | Parameter | Test condition (note 1) | MIN | MAX | Units |
|-------------------|--------------------|--|------|----------------|-------|
| V_{IH} | Input High Voltage | $V_{OUT} \ge V_{OH (min)} or$ | 2 | $V_{DD} + 0.3$ | V |
| V_{IL} | Input Low Voltage | $V_{OUT} \le V_{OL (max)}$ | -0.3 | 0.8 | V |
| I _{IN} | Input Current | $V_{IN} = 0 \text{ V or } V_{IN} = V_{DD}$ | | ±5 | μΑ |

Note: Vdd = 3.3V, unless specified otherwise

Table 16: Komodo Fiber LVTTL input specifications

| Symbol | Parameter | Test condition | MIN | MAX | Units |
|-------------------|---------------------|--------------------------------|-----|-----|-------|
| V_{OH} | Output High Voltage | $V_{DD} = min, I_{OH} = -2 mA$ | 2.4 | | V |
| $V_{ m OL}$ | Output Low Voltage | $V_{DD} = min, I_{OL} = 2 mA$ | | 0.4 | V |

Note: Vdd = 3.3V, unless specified otherwise

Table 17: Komodo Fiber LVTTL output specifications

| Symbol | Parameter | Test condition (note 1) | MIN | MAX | Units |
|-------------------|--------------------|--|------|-----|-------|
| V_{IH} | Input High Voltage | $V_{OUT} \ge V_{OH (min)}$ or | 2 | 5 | V |
| V_{IL} | Input Low Voltage | $V_{OUT} \le V_{OL (max)} 0$ | -0.3 | 0.8 | V |
| I_{IN} | Input Current | $V_{IN} = 0 \text{ V or } V_{IN} = V_{DD}$ | | ±5 | μΑ |

Note: Vdd = 5V, unless specified otherwise

Table 18: Komodo Fiber TTL input specifications

| | Symbol | Parameter | Test condition | MIN | MAX | Units |
|---|----------|---------------------|---|-----|-----|-------|
| ſ | V_{OH} | Output High Voltage | $V_{DD} = min$, $I_{OH} = -2 \text{ mA}$ | 4 | | V |
| ſ | V_{OL} | Output Low Voltage | $V_{DD} = min, I_{OL} = 2 mA$ | | 0.4 | V |

Note: Vdd = 5V, unless specified otherwise

Table 19: Komodo Fiber TTL output specifications

| Parameter | Description | Minimum | Typical | Maximum |
|------------------------|---|---------|---------|---------|
| V_{cc} | Supply voltage | 11 V | 12V | 13 V |
| I _{cc} (Host) | Supply Current from PoCL or external power supply | - | 0.9 A | 1.2 A |
| Icc (Device) | ce) Supply Current from external power supply | | 1.7 A | 2 A |
| I _{PoCL} | PoCL Output current per link | 0 A | - | 0.4 A |

Table 20: KY-CL2F Operating conditions

Electrical characteristics for KY-CL2F board IO's:

| Symbol | Parameter | Test condition (note 1) | MIN | MAX | Units |
|-------------------|--------------------|--|-----|-----|-------|
| V_{IH} | Input High Voltage | $V_{OUT} \ge V_{OH (min)} or$ | 3.5 | 5 | V |
| V_{IL} | Input Low Voltage | $V_{OUT} \le V_{OL (max)} 0$ | 0 | 1.5 | V |
| I_{IN} | Input Current | $V_{IN} = 0 \text{ V or } V_{IN} = V_{DD}$ | | ±2 | μA |

Note: Vdd = 5V, unless specified otherwise

Table 21: KY-CL2F TTL input specifications

| Symbol | Parameter | Test condition | MIN | MAX | Units |
|-------------------|---------------------|----------------|-----|-----|-------|
| V_{OH} | Output High Voltage | | 4 | | V |
| $V_{ m OL}$ | Output Low Voltage | | | 0.6 | V |

Note: Vdd = 5V, unless specified otherwise

Table 22: KY-CL2F TTL output specifications

| Symbol | Parameter | Condition | | MIN | Тур | MAX | Units |
|---|---|----------------------------------|----------------|-----|-------|-----|-------|
| V_{OD} | Differential Output Voltage | $R_{\rm L} = 100$ | Ω (RS422) | 2 | 2.7 | | V |
| | | $R_L = 54 \Omega$ | 2 (RS485) | 1.5 | 2.3 | 3.3 | V |
| ΔV_{OD} ΔV_{OS} | Change in Magnitude of V _{OD} for Complementary Output States Change in Magnitude of V _{OS} for | $R_{L} = 100 \Omega / 54 \Omega$ | | | 0.01 | 0.2 | V |
| ΔVOS | Complementary Output States | K L = 100 | 22 / JT 22 | | 0.01 | 0.2 | * |
| Ios | Output Short Circuit Current | | | | | 250 | mA |
| | | Out | $V_{IN} = 12V$ | | 14 | 20 | |
| | | enabled | $V_{IN} = -7V$ | -20 | -11 | | |
| I_{OFF} | Power-off Leakage | Out | $V_{IN} = 12V$ | | 0.03 | 1 | μA |
| | | disabled | $V_{IN} = -7V$ | -1 | -0.01 | | |
| I_{OZ} | Output TRI-STATE Current | | | -1 | | 1 | μΑ |
| V _{OH} | Output High Voltage | | | 2.9 | | | V |
| V _{OL} | Output Low Voltage | | | | | 0.4 | V |

Table 23: KY-CL2F RS422 / RS485 Output DC specifications (Driver Outputs)

| Symbol | Parameter | Condition | MIN | Тур | MAX | Units |
|----------|-----------------------------------|-------------------------|------|------|------|-------|
| V_{TH} | Differential Input High Threshold | | -0.2 | | 0.2 | V |
| I_{IN} | | $V_{IN} = 12 \text{ V}$ | | 0.6 | 1 | μA |
| | Input Current | $V_{IN} = -7 V$ | | -0.3 | -0.8 | μA |
| V_{IH} | Input High Voltage | | 2 | | | V |
| V_{IL} | Input Low Voltage | | | | 0.8 | V |

Table 24: KY-CL2F RS422 / RS485 Input DC specifications (Receiver Inputs)

| Symbol | Parameter | Test condition (note 1) | MIN | MAX | Units |
|-------------------|--------------------|--|-----|-----|-------|
| V_{IH} | Input High Voltage | $V_{OUT} \ge V_{OH (min)} or$ | 5 | | V |
| V_{IL} | Input Low Voltage | $V_{OUT} \le V_{OL (max)} 0$ | -5 | | V |
| I _{IN} | Input Current | $V_{IN} = 0 \text{ V or } V_{IN} = V_{DD}$ | | 1 | μA |

Note: Vdd = 5V, unless specified otherwise

Table 25: KY-CL2F RS4232 input specifications

| Symbol | Parameter | Test condition | MIN | MAX | Units |
|-------------------|---------------------|----------------|-----|-----|-------|
| V_{OH} | Output High Voltage | | 2.7 | | V |
| V_{OL} | Output Low Voltage | | | 0.4 | V |

Note: Vdd = 5V, unless specified otherwise

Table 26: KY-CL2F RS4232 output specifications

10.3 Absolute maximum ratings for GPIO

| Specification | Minimum voltage [V] | Maximum voltage [V] |
|---------------------|---------------------|---------------------|
| LVDS | -0.3 | 3.6 |
| Opto-isolated (in) | -6 | 60 |
| Opto-isolated (out) | -7 | 70 |
| TTL | -0.5 | 6 |
| LVTTL | -0.5 | 3.9 |

Note: The maximum current that the Opto-isolated (out) IOs can support is 150mA

Table 27: Absolute maximum ratings for GPIO



11.1 Komodo Fiber dimensions

The Komodo Fiber board is a half-length PCIe card according to PCI Express Card Electromechanical Specification.

The exact board mechanical dimensions are as defined in Figure 15.

For more detailed information please, contact KAYA Instruments representative.

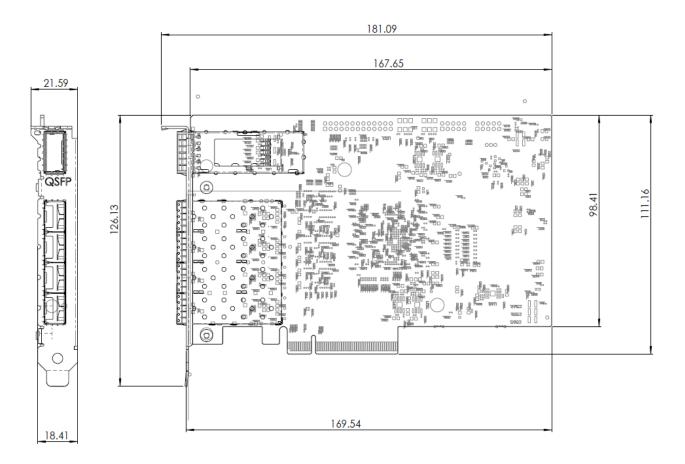


Figure 15: PCB Mechanical Dimensions

11.2 KY-CL2F Dimensions

Each KY-CL2F unit is housed in a metal enclosure as shown in Figure 16.

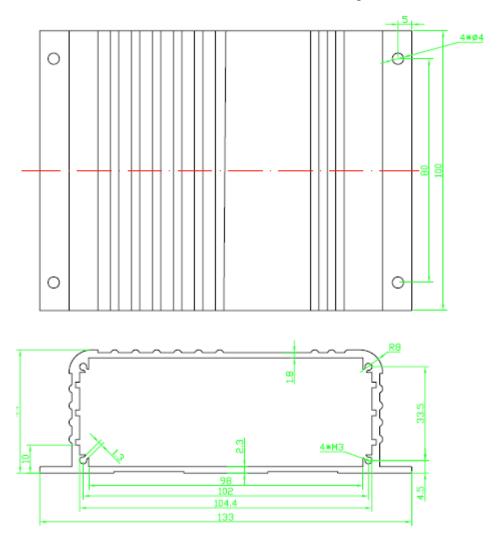


Figure 16: External dimensions of the KY-CL2F enclosure box

11.3 Camera Link cables

Camera Link® is a robust communications link using a dedicated cable connection and a standardized communications protocol. Camera Link is a hardware specification that standardizes the connection between cameras and frame grabbers. It defines a complete interface which



includes provisions for data transfer, camera timing, serial communications, and real time signaling to the camera. Camera Link was built for real time, high bandwidth (maximum 850 MB/s) parallel communication. It is a well-established and distributed industry standard, and there are many Camera Link products on the market today.

11.4 Fiber cables

Optical fibers are widely used to permits transmission over longer distances and at higher bandwidths than other forms of communication. Fibers are used instead of metal wires because signals travel along them with less loss and are also immune to electromagnetic interference.

Fibers that support many propagation paths or transverse modes are called multi-mode fibers (MMF), while those that only support a single mode are called single-mode fibers (SMF). Multi-mode fibers generally are used for short-distance communication links and for applications where high power must be transmitted. Single-mode fibers are used for most communication links longer than 400 meters (1,200 ft.).





12.1 Ordering information

| Item name | Item part number |
|---------------------------------------|----------------------|
| Camera Link FXCL system | KY-FXCL |
| SFP+ single-mode module | KY-SFP-10G31-10 |
| SFP+ multi-mode module | KY-SFP-10G85-3M |
| SFP+ single-mode bidirectional module | KY-SFP-BD-10G-10 |
| Fiber cable (*) | KY-FCA-X-XX-XX-XXX.X |
| Camera Link Cable (*) | KY-CCL-XX-X.X |
| Power supply 12V, 26W | KY_PWR12_26 |

Table 28: Ordering Information

